EnduraMax 75s Series Brushless Motor with Integral Drive

75 mm (2.95-inch) BLDC Motor with Integrated Sensorless Digital Drive

Allied Motion's Gen III EnduraMaxTM 75s series motors are 75 mm (2.95 in) diameter brushless DC motors that incorporate integrated drive electronics. Patented, sensorless drive technology in the E75s enables variable or fixed speed operation for such applications as blowers, fans, compressors, conveyors, pumps, and similar commercial/ industrial applications.

EnduraMax 75s motors are highly costeffective, compact, and have high power density. The integrated sensorless drive module is contained in a housing that conforms with the diameter of the motor, making it easy to fit the EnduraMax 75s into blower assemblies.

Compared to brush DC motors, the EnduraMax 75s is quieter, has much longer service life, and needs no maintenance, making it the right choice to replace DC motors in mobile HVAC, equipment modernization, and new design applications.

Standard EnduraMax 75s winding voltage choices are 12, 24 and 48 VDC, making these motors particularly suited for battery-fed applications. (Alternate winding voltages available via special order.) The E75s provides continuous shaft power up to 245 W and rated torque of up to 0.85 Nm.

As always with Allied Motion products, custom design versions are available to exactly match application requirements.

Features & Benefits

- Three standard frame lengths with rated, continuous output power up to 245 W
- 12, 24 or 48 VDC winding voltage selections – ideal for battery-powered applications
- Continuous rated torque of up to 0.85 Nm (120 oz-in) and rated speed of up to 4900 RPM
- Wide 20:1 speed control range
- All-digital integrated drive electronics module simplifies wiring

- 0 10 V standard analog speed command input
- I/O: 1 direction input and 1 speed/ status output
- Externally visible status LED
- 5/16-inch cold-rolled steel shaft
- Heavy-duty ball bearings
- Drive electronics protection, including reverse voltage
- IP50 protection level
- Automotive-class drive protection (over-voltage, voltage reversal)
- Class F (155 °C) rated winding

Options & Accessories

- Body-size round end frame (shaft end) instead of square end frame
- 9 or 10 mm diameter shaft
- Non-isolated, J1939 CAN with custom or Allied Motion's standard J1939 protocol
- Low power drive "sleep" mode (available with CAN option only)
- 2-wire input—control the EnduraMax like a DC motor
- PWM speed control
- Potentiometer speed control
- Tailored winding designs to optimize performance
- Customized analog command input voltage ranges
- Sealed ball bearings
- Stainless steel shaft
- IP65 protection level
- Customized shaft, and/or mounting to match application requirements
- Alternate winding voltages available via special order
- Motor winding over-temperature protection
- Sinking and sourcing inputs
- Separate motor-enable input



- Brushless DC motor with integrated drive for torque or speed control applications
- Rated speed up to 4900 RPM
- Continuous output of up to 245 W and 0.85 Nm (120 oz-in)



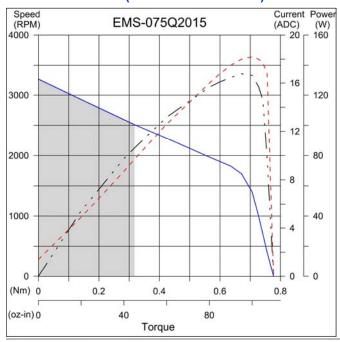


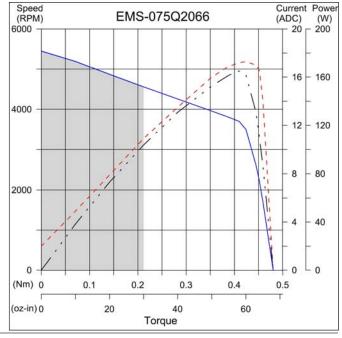
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SPECIFICATIONS (2-STACK MODELS)

	EMS-075Q2015	EMS-075Q2066	EMS-075R2016	EMS-075R2017	EMS-075G2016	EMS-075G2017
	Low Speed	High Speed	Low Speed	High Speed	Low Speed	High Speed
DC Input Voltage [VDC ± 15%]		2	2			8
Rated Cont. Torque [Nm (oz-in)]	0.32 (45)	0.21 (30)	0.35 (50)	0.25 (35)	0.43 (60)	0.35 (50)
Peak Torque [Nm (oz-in)](1)	0.71 (100)	0.42 (60)	1.13 (160)	0.64 (90)	1.13 (160)	1.27 (180)
Rated Speed [RPM]	2500	4600	2600	4900	2400	4550
No-load Speed [RPM]	3200	5300	3350	5650	3100	5200
Rated Cont. Power [W (HP)](2)	85 (0.11)	100 (0.13)	100 (0.13)	140 (0.19)	110 (0.14)	170 (0.23)
DC Input Current [ADC]	11.0	11.0	6.6	8.3	3.4	5.0
Power Derating Above 23°C [W/°C (W/°F)]	0.48 (0.27)	0.96 (0.53)	0.46 (0.25)	1.70 (0.94)	0.89 (0.50)	1.71 (0.95)
Motor Rotor Inertia [E-5 kg-m² (oz-in-sec²)]			1.56 (0			
Weight [kg (lb)]			0.83			
Available Control Modes	Open-loop speed control "OLV" mode (standard), current mode, and velocity mode					
Amplifier Type	PWM (20 kHz) 4-quadrant control					
Current (Torque) Loop Type	DQ PI, 100 µs update time					
Velocity Loop	PID / PDF 200 µ					
Standard Analog Input		10kΩ, 12-bit resolut				
Standard Digital I/O		tion input: +3 to +60			inal draw, sourcing	
		output: open collecto		nA max. sink	5:	
Speed / Status Output		r: 9 pulses per moto				(nominal) output
		nperature fault: 25%		(40))	Status LED: 0	
		Itage or over-voltage circuit fault: 75% dut		e at 10 Hz	slow blink: dis fast blink: ena	,
	Other fault: 10		y cycle at 10 HZ		4 blink+pause	,
Standard Protection Features	I ² T current fol		Reverse polar	ity protect	IP50 protection	
Standard Protection readures	Over-voltage		 Load dump pr 		Locked rotor	
	Short-circuit protect Drive over-temperature protect after three failed start attempts)					
Optional Drive Configuration Features	Customized analog command Sinking and sourcing inputs PWM speed control					
(Contact Allied Motion for Details)	input voltage		Separate motor			J1939 CAN input ⁽⁴⁾
,	Motor winding over-temperature IP65 protection level Potentiometer speed control					
	protect • 2-wire input • And more					
Ambient Storage Temperature	-40 to 125 °C (-4	40 to 257 °F)	•			
70.34	,					

- (1) Maximum of 4 sec.
- (2) With motor mounted to aluminum plate 200 x 200 x 10 mm (8 x 8 x 0.375 in) at 23 °C (derate motor power above 23 °C ambient temperature)
- (3) The user is responsible for checking the details of their power source to determine its ability to accept regenerated energy if produced by the user's system
- (4) The user is responsible for providing CAN isolation if required by the user's system. Available with custom or Allied Motion's standard J1939 protocol

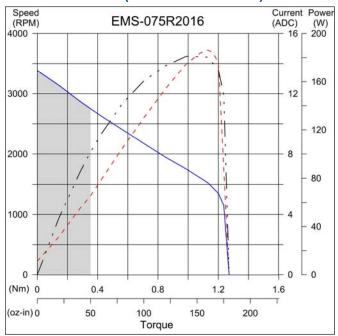


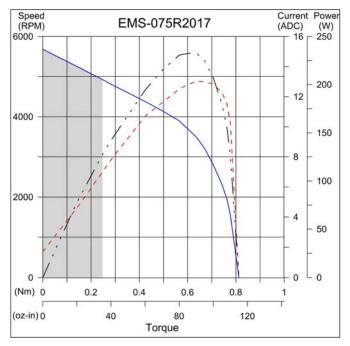


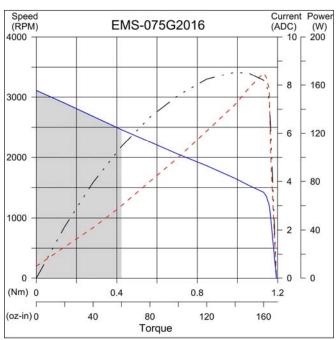
ALCYON

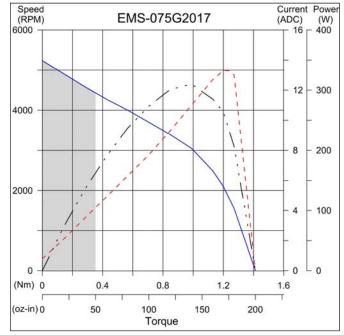
EnduraMax 75s Series Brushless Motor with Integral Drive

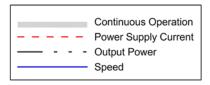
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EnduraMax 75s Series Brushless Motor with Integral Drive

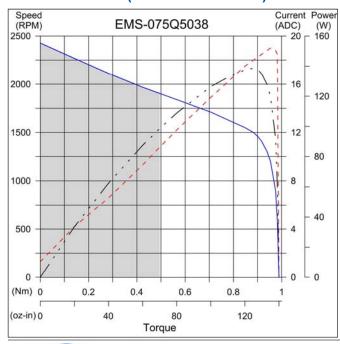
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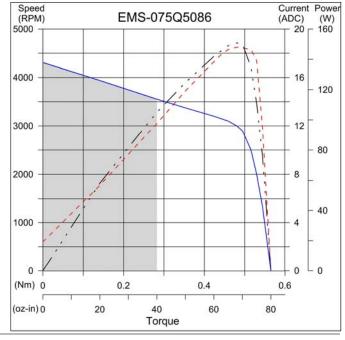
SPECIFICATIONS (5-STACK MODELS)

	EMS-075Q5038	EMS-075Q5086	EMS-075R5039	EMS-075R5040	EMS-075G5039	EMS-075G5040
	Low Speed	High Speed	Low Speed	High Speed	Low Speed	High Speed
DC Input Voltage [VDC ± 15%]	12		2	4	4	8
Rated Cont. Torque [Nm (oz-in)]	0.49 (70)	0.28 (40)	0.56 (80)	0.42 (60)	0.63 (90)	0.46 (65)
Peak Torque [Nm (oz-in)](1)	0.95 (135)	0.49 (70)	1.59 (225)	0.85 (120)	1.84 (260)	1.98 (280)
Rated Speed [RPM]	1900	3600	2000	3750	2200	3800
No-load Speed [RPM]	2400	4250	2550	4200	2650	4200
Rated Cont. Power [W (HP)](2)	100 (0.13)	110 (0.14)	120 (0.16)	165 (0.22)	150 (0.20)	190 (0.25)
DC Input Current [ADC]	12.1	13.1	7.1	9.1	4.3	5.0
Power Derating Above 23°C [W/°C (W/°F)]	0.55 (0.30)	1.23 (0.68)	0.68 (0.38)	1.69 (0.94)	1.22 (0.68)	3.13 (1.74)
Motor Rotor Inertia [E-5 kg-m ² (oz-in-sec ²)]			2.48 (0	.0035)		
Weight [kg (lb)]			1.11	(2.44)		
Available Control Modes	Open-loop spee	d control "OLV" mod	e (standard), current	mode, and velocity	mode	
Amplifier Type	PWM (20 kHz) 4-quadrant control					
Current (Torque) Loop Type	DQ PI, 100 µs update time					
Velocity Loop	PID / PDF 200 µ					
Standard Analog Input		10kΩ, 12-bit resolut				
Standard Digital I/O		ction input: +3 to +60 output: open collector			inal draw, sourcing	
Speed / Status Output		r: 9 pulses per moto	<u> </u>		Disabled: 0 V	(nominal) output
	1 '	nperature fault: 25%			Status LED: 0	' '
	Bus under-vo	Itage or over-voltage	fault: 50% duty-cycl	e at 10 Hz	slow blink: dis	abled;
	Stall or short-	circuit fault: 75% dut	y cycle at 10 Hz		fast blink: ena	bled;
	Other fault: 10				4 blink+pause	
Standard Protection Features	I ² T current fol		 Reverse polar 	, ,	 IP50 protection 	
	Over-voltage detection ⁽³⁾ Load dump protect Locked rotor protect (disable after					
	Short-circuit protect Drive over-temperature protect three failed start attempts)					
Optional Drive Configuration Features	Customized analog command Sinking and sourcing inputs PWM speed control					
(Contact Allied Motion for Details)	input voltage ranges • Separate motor-enable input • Non-isolated, J1939 CAN input ⁽⁴⁾					
	Motor winding over-temperature IP65 protection level Potentiometer speed control And more					
Ambient Storage Temperature	protect • 2-wire input • And more -40 to 125 °C (-40 to 257 °F)					
(1) Maximum of 4 and	-40 to 125 C (-4	+U (U Z31 F)				

(1) Maximum of 4 sec.

- (2) With motor mounted to aluminum plate 200 x 200 x 10 mm (8 x 8 x 0.375 in) at 23 °C (derate motor power above 23 °C ambient temperature)
- (3) The user is responsible for checking the details of their power source to determine its ability to accept regenerated energy if produced by the user's system
- (4) The user is responsible for providing CAN isolation if required by the user's system. Available with custom or Allied Motion's standard J1939 protocol

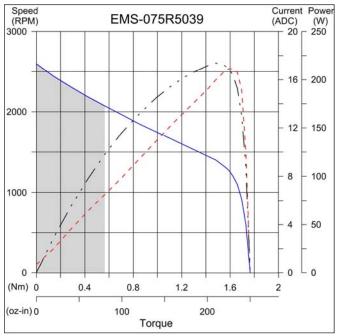


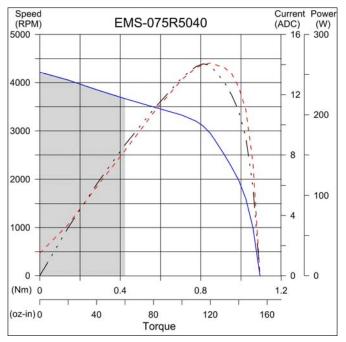


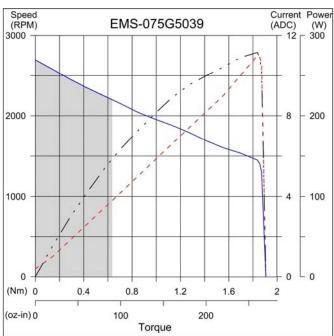
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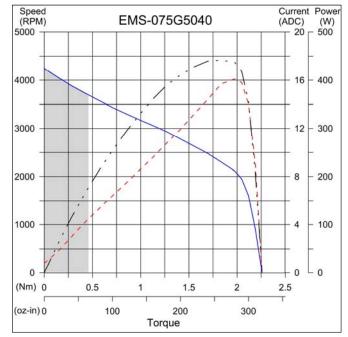
EnduraMax 75s Series Brushless Motor with Integral Drive

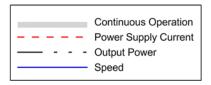
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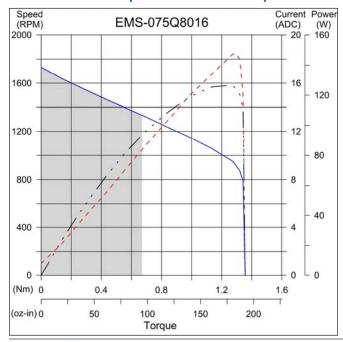
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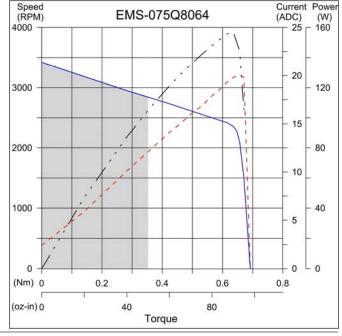
SPECIFICATIONS (8-STACK MODELS)

	EMS-075Q8016	EMS-075Q8064	EMS-075R8017	EMS-075R8018	EMS-075G8017	EMS-075G8018
	Low Speed	High Speed	Low Speed	High Speed	Low Speed	High Speed
DC Input Voltage [VDC ± 15%]		2	2			8
Rated Cont. Torque [Nm (oz-in)]	0.67 (95)	0.35 (50)	0.78 (110)	0.49 (70)	0.85 (120)	0.74 (105)
Peak Torque [Nm (oz-in)](1)	1.27 (180)	0.64 (90)	1.83 (260)	1.13 (160)	2.19 (310)	2.40 (340)
Rated Speed [RPM]	1300	2950	1700	3000	1900	3000
No-load Speed [RPM]	1700	3400	2150	3400	2250	3450
Rated Cont. Power [W (HP)](2)	90 (0.12)	110 (0.15)	140 (0.19)	160 (0.21)	180 (0.24)	245 (0.33)
DC Input Current [ADC]	12.1	13.6	8.6	9.3	5.0	6.6
Power Derating Above 23°C [W/°C (W/°F)]	0.51 (0.28)	1.47 (0.82)	0.92 (0.51)	2.04 (1.14)	1.88 (1.05)	1.82 (1.01)
Motor Rotor Inertia [E-5 kg-m² (oz-in-sec²)]			3.35 (0	.0048)		
Weight [kg (lb)]			1.41	/		
Available Control Modes	Open-loop speed control "OLV" mode (standard), current mode, and velocity mode					
Amplifier Type	PWM (20 kHz) 4-quadrant control					
Current (Torque) Loop Type	DQ PI, 100 µs u					
Velocity Loop	PID / PDF 200 µ	<u> </u>				
Standard Analog Input		10kΩ, 12-bit resolu				
Standard Digital I/O			V (high); 0 to +0.5 or, +60 V max., 100		inal draw, sourcing	
Speed / Status Output		or: 9 pulses per moto	· · · · · · · · · · · · · · · · · · ·	IIA IIIax. SIIIK	- Disabled: 0.V	(nominal) output
Speed / Status Output			duty-cycle at 10 Hz		Status LED: 0	
			fault: 50% duty-cycl	e at 10 Hz	slow blink: dis	
		circuit fault: 75% dut		0 41 10 112	fast blink: ena	,
	Other fault: 10		, ,,		4 blink+pause	,
Standard Protection Features	 I²T current fol 	dback	Reverse polar	ity protect	IP50 protection	n level
	 Over-voltage 		 Load dump pr 	otect	 Locked rotor r 	protect (disable after
	Short-circuit protect Drive over-temperature protect three failed start attempts)					
Optional Drive Configuration Features	 Customized a 		 Sinking and se 		 PWM speed of 	
(Contact Allied Motion for Details)	input voltage ranges • Separate motor-enable input • Non-isolated, J1939 CAN input ⁽⁴⁾					
	Motor winding over-temperature Potentiometer speed control					
A 11 101 T	protect • 2-wire input • And more					
Ambient Storage Temperature	-40 to 125 °C (-4	40 to 257 °F)				

(1) Maximum of 4 sec.

- (2) With motor mounted to aluminum plate 200 x 200 x 10 mm (8 x 8 x 0.375 in) at 23 °C (derate motor power above 23 °C ambient temperature)
- (3) The user is responsible for checking the details of their power source to determine its ability to accept regenerated energy if produced by the user's system
- (4) The user is responsible for providing CAN isolation if required by the user's system. Available with custom or Allied Motion's standard J1939 protocol

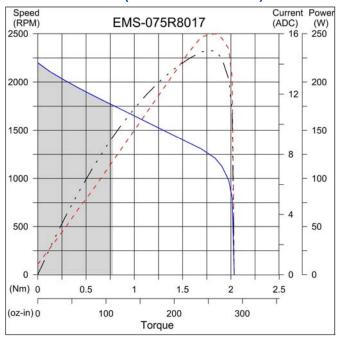


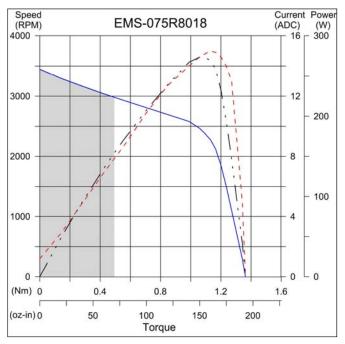


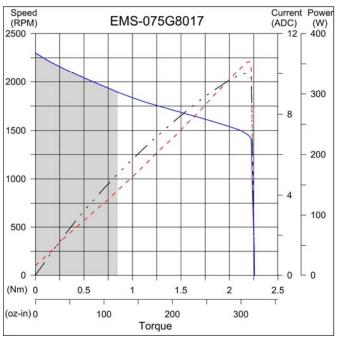
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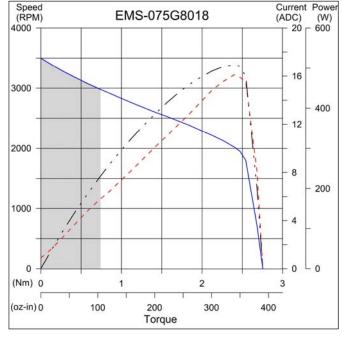
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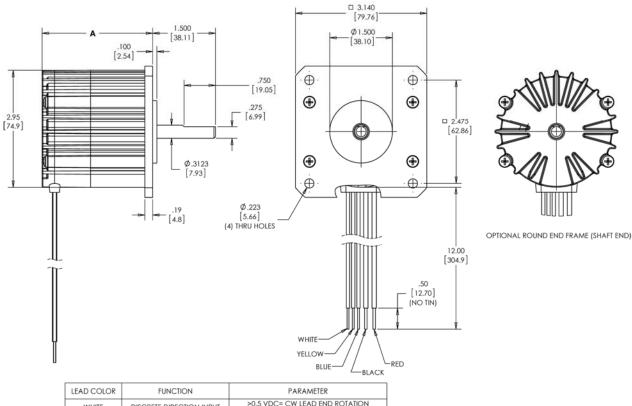








DIMENSIONS



LEAD COLOR	FUNCTION	PARAMETER
WHITE	DISCRETE DIRECTION INPUT	>0.5 VDC= CW LEAD END ROTATION <0.5 VDC=CCW LEAD END ROTATION
YELLOW	ANALOG VOLTAGE SPEED COMMAND INPUT	0 TO 10.0 VDC
BLUE	DISCRETE OPEN COLLECTOR SPEED/DIAGNOSTICS OUTPUT	50% DUTY CYCLE SQUARE WAVE AT A FREQUENCY OF 9 CYCLES PER REVOLUTION
BLACK	NEGATIVE DRIVE POWER SUPPLY VOLTAGE	12VDC NOM: 9VDC MIN TO 18VDC MAX
RED	POSITIVE DRIVE POWER SUPPLY VOLTAGE	24VDC NOM: 18VDC MIN TO 36VDC MAX 48VDC NOM: 36VDC MIN TO 54VDC MAX

Dimensions in "inches (millimeters)"



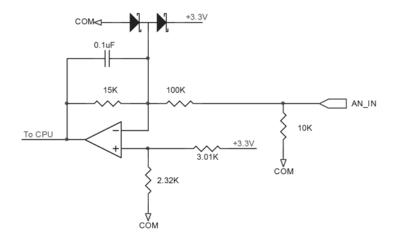
MODEL	2-STACK	5-STACK	8-STACK
Length A [in (mm)]	2.645 (68)	3.196 (82)	3.747 (96)



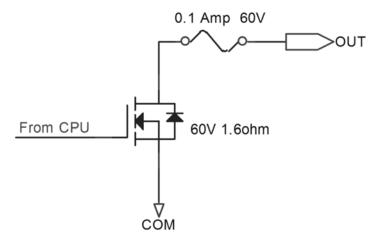
EnduraMax 75s Series Brushless Motor with Integral Drive

STANDARD I/O CIRCUIT DRAWINGS

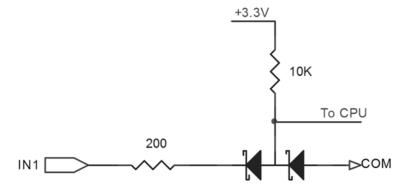
SPEED CONTROL ANALOG INPUT



SPEED/STATUS SINKING OUTPUT



REVERSE DIRECTION SOURCING INPUT



EnduraMax 95s Series Brushless Motor with Integral Drive

95 mm (3.77-inch) BLDC Motor with Integrated Sensorless Digital Drive

Allied Motion's Gen III EnduraMax 95s series motors are 95 mm (3.77 in) diameter brushless DC motors that incorporate integrated drive electronics. Patented, sensorless drive technology in the E95s enables variable or fixed speed operation for such applications as blowers, fans, compressors, conveyors, pumps, and similar commercial/industrial applications.

EnduraMax 95s motors are highly costeffective, compact, and have high power density. The integrated sensorless drive module is contained in a housing that conforms with the diameter of the motor for easier fitting in tight space claims.

Compared to brush DC motors, the EnduraMax 95s is quieter, has much longer service life, and needs no maintenance, making it the right choice to replace DC motors in equipment modernizations and in new designs.

Standard EnduraMax 95s winding voltage choices are 12, 24 and 48 VDC, making these motor-drives particularly suited for battery-fed applications. (Alternate winding voltages available via special order.) The E95s provides continuous shaft power up to a nominal 360 W and rated torque of up to 1.7 Nm.

As with all Allied Motion products, custom designs can be provided to exactly match application requirements.

Features & Benefits

- Three standard frame lengths with rated, continuous output power up to 360 W
- 12, 24 or 48 VDC winding voltage selections ideal for battery-powered applications
- Continuous rated torque of up to 1.7 Nm (240 oz-in) and rated speed of up to 4900 RPM
- Wide 20:1 speed control range

- All-digital integrated drive electronics module simplifies wiring
- 0 10 V standard analog speed command input
- I/O: 1 direction input and 1 speed/ status output
- Externally visible status LED
- 0.5-inch (12.7 mm) cold-rolled steel shaft
- Heavy-duty ball bearings
- Drive electronics protection, including reverse voltage
- IP50 protection level
- Automotive-class drive system protection (over-voltage, voltage reversal)
- Class F (155 °C) rated winding

Options & Accessories

- Non-isolated, J1939 CAN with a custom or Allied Motion's standard J1939 protocol
- Low power drive "sleep" mode (available with CAN option only)
- 2-wire version—control the EnduraMax like a DC motor
- PWM speed control
- Potentiometer speed control
- Tailored winding designs to optimize performance
- Customized analog command input voltage ranges
- · Sealed ball bearings
- · Stainless steel shaft
- IP65 protection level
- Customized shaft, and/or mounting to match application requirements
- Alternate winding voltages available via special order
- Motor winding over-temperature protection
- Sinking and sourcing inputs
- Separate motor-enable input



- Brushless DC motor with integrated patented drive for torque or speed control applications
- Rated speed up to 4900 RPM with 20:1 speed control range
- Continuous output of up to 360 W and 1.7 Nm



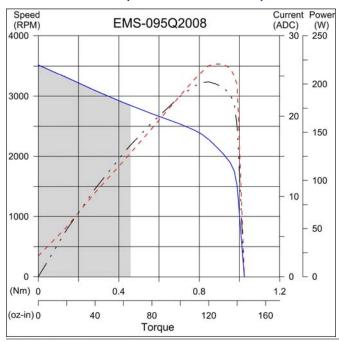


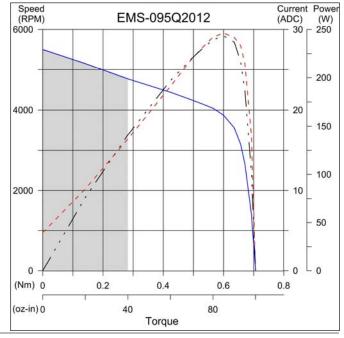
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SPECIFICATIONS (2-STACK MODELS)

	EMS-095Q2008	EMS-095Q2012	EMS-095R2009	EMS-095R2010	EMS-095G2009	EMS-095G2010
	Low Speed	High Speed	Low Speed	High Speed	Low Speed	High Speed
DC Input Voltage [VDC ± 15%]	1	2	2		48	
Rated Cont. Torque [Nm (oz-in)]	0.46 (66)	0.46 (66) 0.28 (40)		0.39 (56)	0.71 (101)	0.53 (75)
Peak Torque [Nm (oz-in)] ⁽¹⁾	0.85 (120)	0.60 (85)	1.84 (260)	1.41 (200)	2.11 (300)	2.05 (290)
Rated Speed [RPM]	2850	4900	2500	4700	2400	4600
No-load Speed [RPM]	3500	5500	3250	5300	3100	5400
Rated Cont. Power [W (HP)] ⁽²⁾	140 (0.19)	150 (0.20)	175 (0.23)	200 (0.27)	180 (0.24)	260 (0.35)
DC Input Current [ADC]	16.1	17.2	10.4	11.0	5.3	7.6
Power Derating Above 23°C [W/°C (W/°F)]	1.15 (0.64)	3.03 (1.69)	1.22 (0.68)	1.64 (0.91)	1.20 (0.67)	1.87 (1.04)
Motor Rotor Inertia [E-5 kg-m ² (oz-in-sec ²)]			6.10 (0	0.0086)		
Weight [kg (lb)]			1.33 ((2.93)		
Available Control Modes	Open-loop speed control "OLV" mode (standard), current mode, and velocity mode					
Amplifier Type	PWM (20 kHz) 4-quadrant control					
Current (Torque) Loop Type	DQ PI, 100 μs u					
Velocity Loop	PID / PDF 200 μ	is update time				
Standard Analog Input		10kΩ, 12-bit resolut				
Standard Digital I/O		tion input: +3 to +60			inal draw, sourcing	
		output: open collecto		mA max. sink		
Speed / Status Output		r: 9 pulses per motor			Other fault: 10	
		nperature fault: 25%		1 10 11-		(nominal) output
		tage or over-voltage circuit fault: 75% duty		e at 10 Hz	Externally visi potifies user a	of motor condition
Standard Protection Features	I ² T current fol		Reverse polar	ity protect	IP50 protect le	
Standard Fotostion Fedures	Over-voltage		 Load dump pr 			protect (disable after
	Short-circuit protect Drive over-temperature protect three failed start attempts)					
Optional Drive Configuration Features	Customized analog command Sinking and sourcing inputs PWM speed control				ontrol	
(Contact Allied Motion for Details)	input voltage		 Separate motor 			J1939 CAN input ⁽⁴⁾
	Motor winding over-temperature IP65 protection level Potentiometer speed control			speed control		
	protect • 2-wire input • And more					
Ambient Storage Temperature	-40 to 125 °C (-4	10 to 257 °F)				

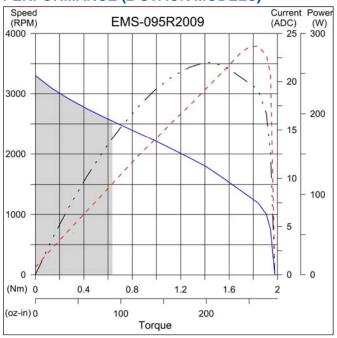
- (1) Maximum of 4 sec.
- (2) With motor mounted to aluminum plate 200 x 200 x 10 mm (8 x 8 x 0.375 in) at 23 °C (derate motor power above 23 °C ambient temperature)
- (3) The user is responsible for checking the details of their power source to determine its ability to accept regenerated energy if produced by the user's system
- (4) The user is responsible for providing CAN isolation if required by the user's system. Available with custom or Allied Motion's standard J1939 protocol

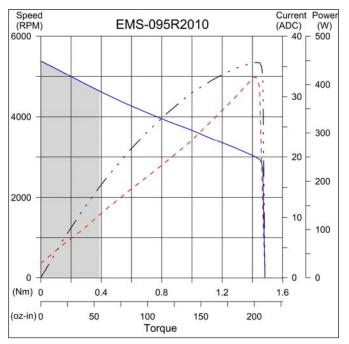


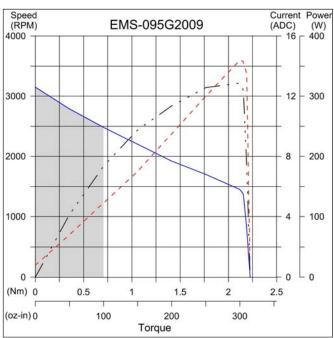


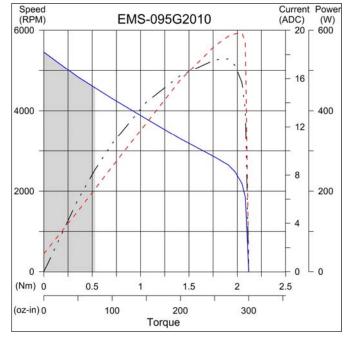


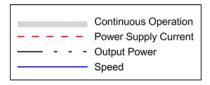
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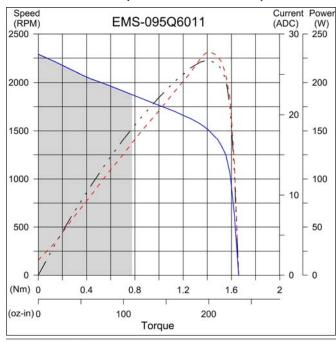
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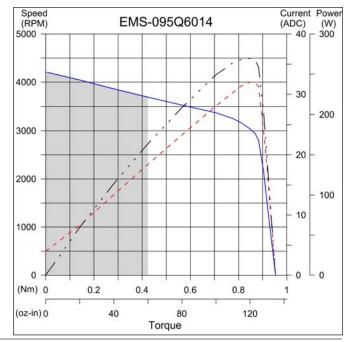
SPECIFICATIONS (6-STACK MODELS)

•	•					
	EMS-095Q6011	EMS-095Q6014	EMS-095R6012	EMS-095R6013	EMS-095G6012	EMS-095G6013
	Low Speed	High Speed	Low Speed	High Speed	Low Speed	High Speed
DC Input Voltage [VDC ± 15%]	1	12	2		48	
Rated Cont. Torque [Nm (oz-in)]	0.77 (110)	0.42 (60)	1.10 (157)	0.60 (85)	1.13 (161)	0.71 (101)
Peak Torque [Nm (oz-in)] ⁽¹⁾	1.41 (200)	0.85 (120)	2.90 (410)	1.34 (190)	2.97 (420)	2.68 (380)
Rated Speed [RPM]	1900	3850	1650	3850	2100	4000
No-load Speed [RPM]	2250	4150	2100	4200	2600	4350
Rated Cont. Power [W (HP)](2)	155 (0.21)	170 (0.23)	195 (0.26)	255 (0.34)	260 (0.35)	300 (0.40)
DC Input Current [ADC]	17.2	18.9	11.0	13.8	6.9	7.7
Power Derating Above 23°C [W/°C (W/°F)]	1.17 (0.65)	2.73 (1.52)	1.26 (0.70)	2.61 (1.45)	1.98 (1.10)	3.84 (2.14)
Motor Rotor Inertia [E-4 kg-m² (oz-in-sec²)]			1.17 (0).0166)		
Weight [kg (lb)]			1.93	(4.24)		
Available Control Modes	Open-loop spee	d control "OLV" mod	e (standard), current	mode, and velocity	mode	
Amplifier Type	PWM (20 kHz) 4-quadrant control					
Current (Torque) Loop Type	DQ PI, 100 µs u	•				
Velocity Loop	PID / PDF 200 µ	us update time				
Standard Analog Input	0 to +10.0 VDC,	, 10kΩ, 12-bit resolu	tion			
Standard Digital I/O	Reverse direct Speed/status	ction input: +3 to +60 output: open collected	V (high); 0 to +0.5 ۱ or, +60 V max., 100 ا	V (low) at 3 mA nom mA max. sink	inal draw, sourcing	
Speed / Status Output	 Speed monitor: 9 pulses per motor revolution Drive over-temperature fault: 25% duty-cycle at 10 Hz Bus under-voltage or over-voltage fault: 50% duty-cycle at 10 Hz Stall or short-circuit fault: 75% duty cycle at 10 Hz Other fault: 100% duty cycle Disabled: 0 V (nominal) outputy Externally visible status LED notifies user of motor condition 				(nominal) output ble status LED of motor condition	
Standard Protection Features	 I²T current foldback Over-voltage detect⁽³⁾ Short-circuit protect Peverse polarity protect Load dump protect Locked rotor protect (disable after three failed start attempts) 				orotect (disable after art attempts)	
Optional Drive Configuration Features (Contact Allied Motion for Details) Ambient Storage Temperature	 Customized analog command input voltage ranges Motor winding over-temperature protect Sinking and sourcing inputs Separate motor-enable input IP65 protection level 2-wire input PWM speed control Non-isolated, J1939 CAN input^(c) Potentiometer speed control And more 				J1939 CAN input(4)	
Ambient Storage Temperature	-40 to 125 C (-4	10 10 231 1)				

⁽¹⁾ Maximum of 4 sec.

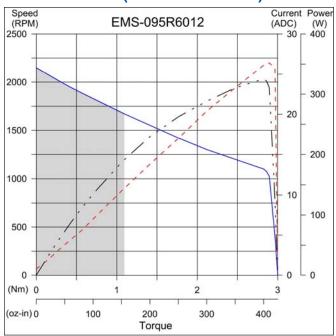
- (2) With motor mounted to aluminum plate 200 x 200 x 10 mm (8 x 8 x 0.375 in) at 23 °C (derate motor power above 23 °C ambient temperature)
- (3) The user is responsible for checking the details of their power source to determine its ability to accept regenerated energy if produced by the user's system
- (4) The user is responsible for providing CAN isolation if required by the user's system. Available with custom or Allied Motion's standard J1939 protocol

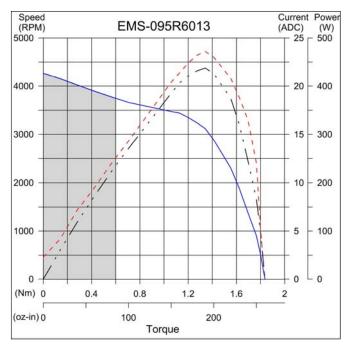


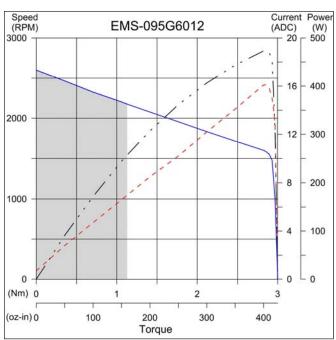


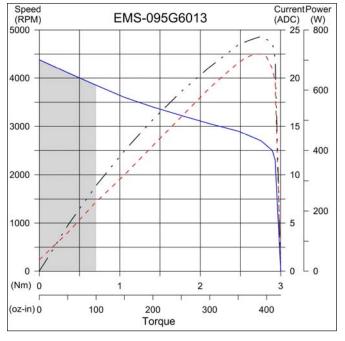


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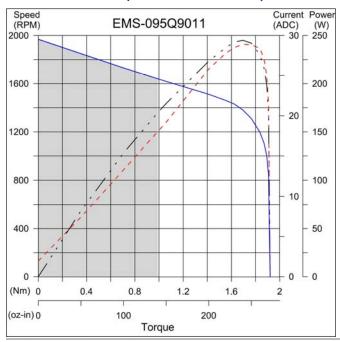


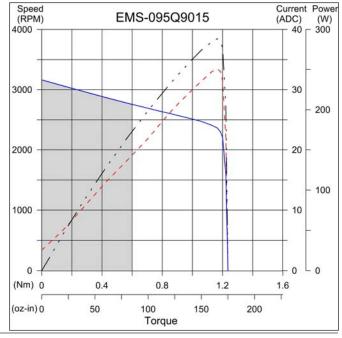
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SPECIFICATIONS (9-STACK MODELS)

	EMS-095Q9011	EMS-095Q9015	EMS-095R9012	EMS-095R9013	EMS-095G9012	EMS-095G9013
	Low Speed	High Speed	Low Speed	High Speed	Low Speed	High Speed
DC Input Voltage [VDC ± 15%]	1	2	2		4	8
Rated Cont. Torque [Nm (oz-in)]	0.98 (140)	0.60 (85)	1.41 (201)	0.81 (115)	1.70 (242)	1.13 (161)
Peak Torque [Nm (oz-in)] ⁽¹⁾	1.69 (240)	1.13 (160)	2.97 (420)	1.84 (260)	2.97 (420)	2.97 (420)
Rated Speed [RPM]	1650	2800	1450	3000	1500	3000
No-load Speed [RPM]	1900	3100	1750	3150	1850	3150
Rated Cont. Power [W (HP)](2)	170 (0.23)	180 (0.24)	220 (0.30)	260 (0.35)	270 (0.36)	360 (0.48)
DC Input Current [ADC]	19.1	20.0	12.3	13.6	7.2	9.2
Power Derating Above 23°C [W/°C (W/°F)]	1.80 (1.00)	2.26 (1.26)	1.40 (0.78)	3.45 (1.92)	2.81 (1.56)	4.35 (2.42)
Motor Rotor Inertia [E-4 kg-m² (oz-in-sec²)]			1.73 (0	.0245)		
Weight [kg (lb)]			2.55 ((5.62)		
Available Control Modes	Open-loop speed control "OLV" mode (standard), current mode, and velocity mode					
Amplifier Type	, ,	1-quadrant control				
Current (Torque) Loop Type	DQ PI, 100 μs ι	update time				
Velocity Loop	PID / PDF 200 µ	us update time				
Standard Analog Input		, 10kΩ, 12-bit resolu				
Standard Digital I/O		ction input: +3 to +60			inal draw, sourcing	
	· ·	output: open collecto	· · · · · · · · · · · · · · · · · · ·	mA max. sink		
Speed / Status Output		or: 9 pulses per moto			Other fault: 10	
		mperature fault: 25%		o ot 10 I I=	 Disabled: 0 V Externally visi 	(nominal) output
		Itage or over-voltage circuit fault: 75% dut		e at 10 HZ		f motor condition
Standard Protection Features	I ² T current fol		Reverse polar	ity protect	IP50 protect le	
Cianan a riotosion riotata so	Over-voltage		 Load dump pr 			protect (disable after
	Short-circuit protect Drive over-temperature protect three failed start attempts)					
Optional Drive Configuration Features	Customized analog command Sinking and sourcing inputs PWM speed control					
(Contact Allied Motion for Details)	input voltage ranges • Separate motor-enable input • Non-isolated, J1939 CAN input ⁽⁴⁾					
	Motor winding over-temperature IP65 protection level Potentiometer speed control					
	protect	10 (055 05)	2-wire input		And more	
Ambient Storage Temperature	-40 to 125 °C (-4	40 to 25/ °F)				

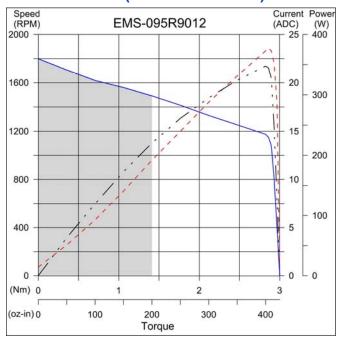
- (1) Maximum of 4 sec.
- (2) With motor mounted to aluminum plate 200 x 200 x 10 mm (8 x 8 x 0.375 in) at 23 °C (derate motor power above 23 °C ambient temperature)
- (3) The user is responsible for checking the details of their power source to determine its ability to accept regenerated energy if produced by the user's system
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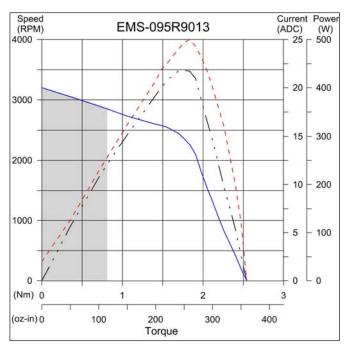


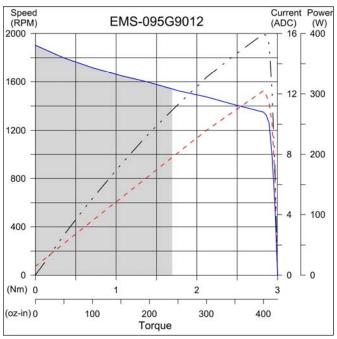


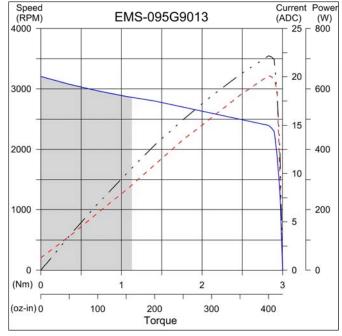


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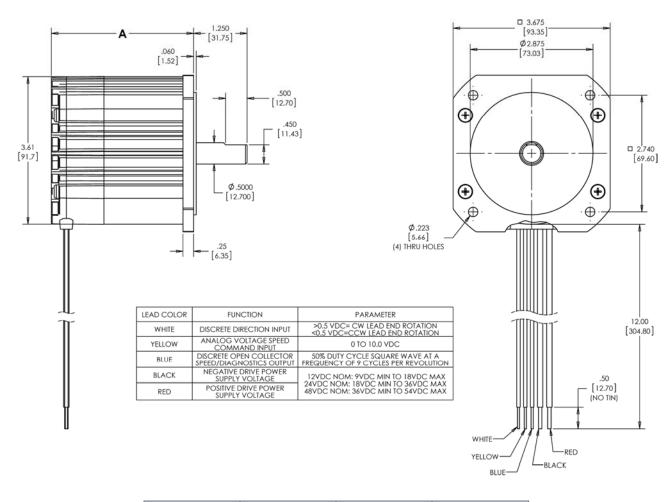






Enduraniax 000 Corios Brasinoso motor with integral Briv

DIMENSIONS

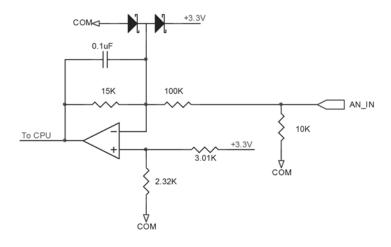


MODEL	MODEL 2-STACK		9-STACK		
Length A [in (mm)]	3.330 (85)	4.080 (104)	4.830 (123)		

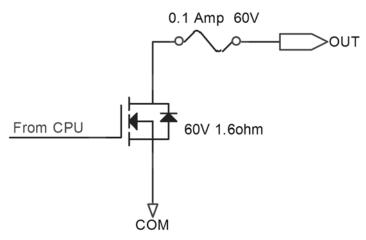


STANDARD I/O CIRCUIT DRAWINGS

SPEED CONTROL ANALOG INPUT



SPEED/STATUS SINKING OUTPUT



REVERSE DIRECTION SOURCING INPUT

