

SPI Signal Conditioner for Electrolytic Tilt Sensors Part Number: 1-6200-005

| Operating Specifications ¹ | |
|---------------------------------------|--------------------------------|
| Interface | SPI |
| Analog Input Resolution | 16 bits (10 bits oversampled) |
| Operating Range | 0% to 100% of sensor range |
| Supply Voltage | 3.3 V DC to 5 V DC |
| Supply Current | 6 mA @ 5 V DC, 4 mA @ 3.3 V DC |
| Operating Temperature | -40 °C to 85 °C |
| Storage Temperature | -40 °C to 125 °C |
| Sensors Controlled | 1 or 2 |
| Axes of Measurement | 1 or 2 |
| Temperature Sensor Range | -40 °C to 125 °C |

| Dimensions | |
|-------------------------------|-------------------------------|
| Housing | None |
| Electrical Connections | 7 Pin, 2.54 mm (0.1") spacing |
| Weight | 4 g |
| Length | 32 mm (1.25") |
| Width | 32 mm (1.25") |
| Hole Center | 27 mm (1.05") |

| SPI Commands, ASCII and Hexadecimal Values | |
|--|---|
| '1', 0x31 | X axis high byte of 16 bit output |
| '2', 0x32 | X axis low byte of 16 bit output |
| '3', 0x33 | Y axis high byte of 16 bit output |
| '4', 0x34 | Y axis low byte of 16 bit output |
| '5', 0x35 | Board temperature high byte of 10 bit output |
| '6', 0x36 | Board temperature low byte of 10 bit output |
| '9', 0x39 | Update all data (software version 2.0.0 and higher) |

Note: Use 1 ms delays between commands.

| Electrical Connections | |
|------------------------|--------------------------------------|
| J1 Pin 1 (+5) | Supply (+) |
| J1 Pin 2 (C) | Supply (-) |
| J1 Pin 3 (C) | Ground |
| J1 Pin 4 (OUT) | SDO, SPI slave data output |
| J1 Pin 5 (IN) | SDI, SPI slave data input |
| J1 Pin 6 (CLK) | SCK, SPI slave clock input |
| J1 Pin 7 (/SS) | SPI slave select |
| L1 | Dual axis sensor connection |
| J3 | Single axis sensor x axis connection |
| J4 | Single axis sensor y axis connection |

Benefits

- Very low power consumption
- Simple integration
- Excellent resolution and repeatability of measurements
- Superior performance in extreme temperatures and environments
- Excellent customer support
- Manufactured in the United States of America



Description

The 1-6200-005 SPI signal conditioner can be used with any Fredericks electrolytic tilt sensor. This signal conditioner can be connected to a dual axis tilt sensor or 1 or 2 single axis tilt sensors to provide single or dual axis position measurement over the sensor's range.

Fredericks 0717 series wide range sensors can be mounted directly to the PCB for a complete inclinometer solution. Single axis sensors must be mounted externally to the PCB and connected with wires.

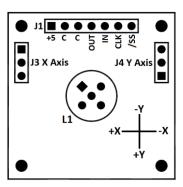
A detailed list of compatible sensors can be found on page 2 in the Related Products section.

Applications

- Recreational vehicle leveling (also known as an RV, caravan, camper van, or motorhome)
- Construction vehicles
- · Geotechnical and structural monitoring
- Laser leveling
- Machine tool leveling
- · Rail track monitoring
- Satellite positioning

View a full list of applications on The Fredericks Company website at www.frederickscompany.com.

Pin Diagram and Direction of Measurement



Note that the direction of measurement only applies when a dual axis sensor is mounted on the PCB.

Certifications and Ratings

• RoHS Compliant

Converting Temperature Values

The board temperature output is a 10-bit value (0 to 1023). To convert that value to a temperature in °C, use the following equation:

Temperature in °C = (((output/1023)*supply voltage)-0.5)/0.01

sales@frederickscompany.com +1 215 947 2500 www.frederickscompany.com 1-6200-005_ds rev J Page 1/2

¹ Visit www.frederickscompany.com for a list of definitions.



SPI Signal Conditioner for Electrolytic Tilt Sensors Part Number: 1-6200-005

| SPI Slave Information | |
|-----------------------|---|
| Clock | From master, idle high, 500 kHz to 20 MHz |
| Data Transfer Edge | Clock high to low |
| Data Bits | 8, MSB first |
| Start Bits | 1 |
| Stop Bits | 1 |
| Slave Select Polarity | Idle high, low when transferring data |

| Related Products | |
|--|----------------------------------|
| Dual Axis Electrolytic Sensors - Metal | |
| 0717-4318-99 | ±60° range, ±0.1° repeatability |
| 0717-4319-99 | ±50° range, ±0.1° repeatability |
| 0717-4313-99 | ±50° range, ±0.05° repeatability |
| 0717-4315-99 | ±60° range, ±0.05° repeatability |
| | |

| 0703-0711-99 | ±3° range, ±0.001° repeatability |
|--------------|-----------------------------------|
| 0703-1602-99 | ±25° range, ±0.005° repeatability |
| | |

Single Axis Electrolytic Sensors - Metal

| Single Axis Electrolytic Sensors - Glass | |
|--|-------------------------------------|
| 0737-0101-99 | ±10° range, ±0.0006° repeatability |
| 0737-1203-99 | ±0.5° range, ±0.0001° repeatability |
| 0711-0763-99 | ±1° range, ±0.0008° repeatability |
| 0711-0768-99 | ±3° range, ±0.0008° repeatability |
| | |

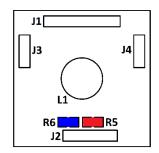
| Single Axis Electrolytic Sensors - Glass Encapsulated | | |
|---|--------------|-------------------------------------|
| | 0719-3705-99 | ±10° range, ±0.0006° repeatability |
| | 0719-3703-99 | ±0.5° range, ±0.0001° repeatability |
| | 0719-1137-99 | ±1° range, ±0.0008° repeatability |
| | 0719-1143-99 | ±3° range, ±0.0008° repeatability |

Board Configuration

The 1-6200-005 signal conditioner can be configured to operate one dual axis sensor or two single axis sensors. This configuration is determined by the resistor values of R5 and R6.

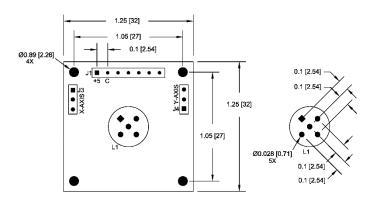
For a dual axis sensor: R5 is 10 k Ω , R6 is not installed. The sensor is connected to L1.

For single axis sensors: R5 is not installed, R6 is 1 k Ω . Sensors are connected to J3 and J4.





Dimensional Drawings



Example SPI Command Sequence

Update data and retrieve X and Y axis tilt values which both return 32768 (0° tilt), transmit and receive values are listed in hexadecimal:

[Master TX] 0x39 //update all values [Master RX] Ignore. //no valid data in buffer yet Delay 1 ms. [Master TX] 0x31 //request x axis high byte [Master RX] 0x2A //'*' response to 0x39 command, data updated Delay 1 ms. [Master TX] 0x32 //request x axis low byte //x axis high byte, response to 0x31 command [Master RX] 0x80 Delay 1 ms. [Master TX] 0x33 //request y axis high byte [Master RX] 0x00 //x axis low byte, response to 0x32 command Delay 1 ms. [Master TX] 0x34 //request y axis low byte [Master RX] 0x80 //y axis high byte, response to 0x31 command Delay 1 ms. [Master TX] 0x39 //update all values [Master RX] 0x00 //y axis low byte, response to 0x32 command

X axis value = $0x8000 = 32768 = 0^{\circ}$ tilt Y axis value = $0x8000 = 32768 = 0^{\circ}$ tilt

Contact Us

The Fredericks Company 2400 Philmont Avenue Huntingdon Valley, PA 19006 tel: +1 215 947 2500 fax: +1 215 947 7464

email: sales@frederickscompany.com web: www.frederickscompany.com

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